# Introduction Power Electronic Device

### Introduction to Power Electronics Device

#### MATLAB/SIMULINK

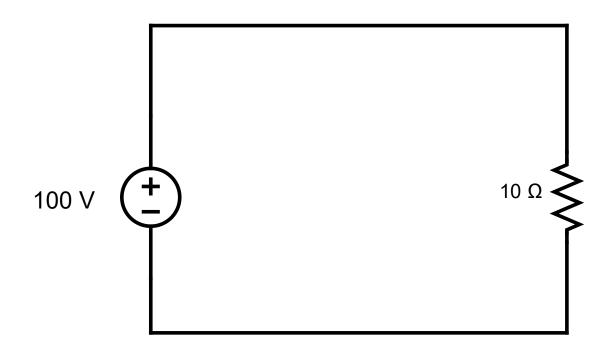
- Design of Electric Circuit.
- Uncontrolled Device
  - Diodes
- Controlled Device
  - Thyristor
  - Mosfet
  - IGBT

Generate Pulses for AC/DC voltage



# Circuit - 1

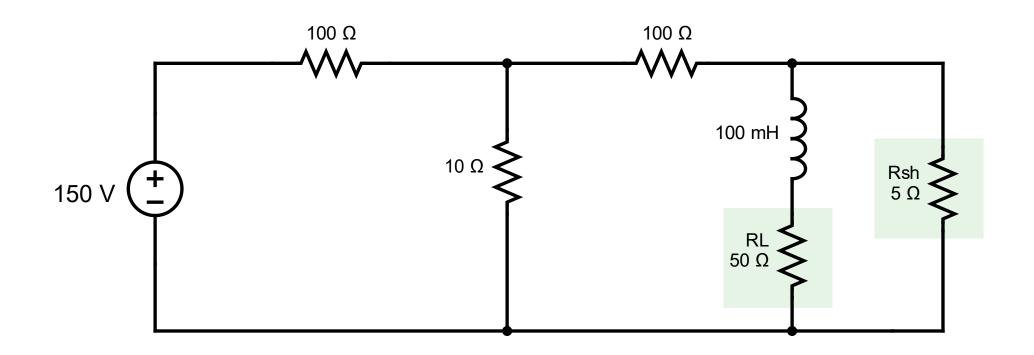
Measure Voltage and Current across  $R_L$ 





# Circuit - 2

Measure Voltage across  $R_L$  and current through  $R_{sh}$  in SIMULINK



# **Uncontrolled Devices**

**Diode Rectifier** 

### Rectifier

A rectifier is a circuit that converts an AC signal into unidirectional signal.

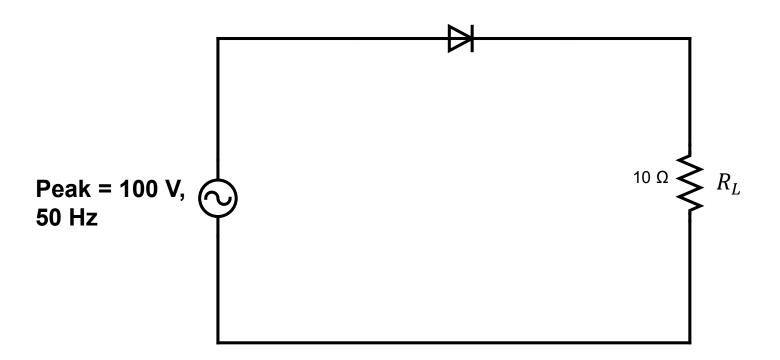
AC to DC converter

### Types of Uncontrolled Rectifier:

- Half Wave Rectifier
- Full Wave Rectifier
- Full Wave Bridge Rectifier

# Half Wave Rectifier

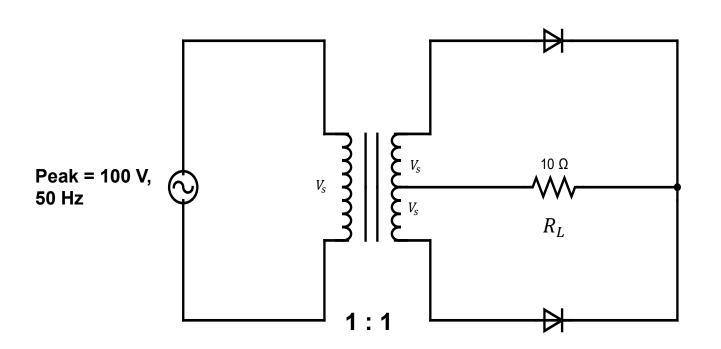
• Visualize voltage and current across  $R_L$ 

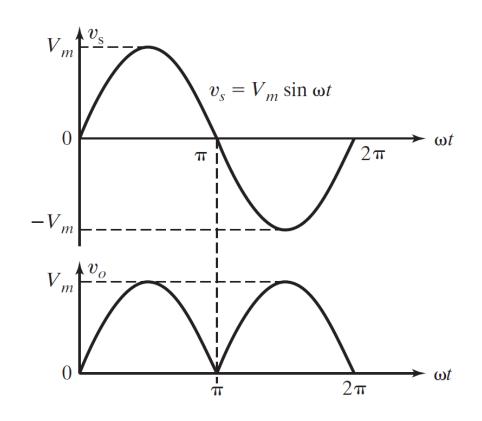


# **Full Wave Rectifier**

CIRCUIT – 2

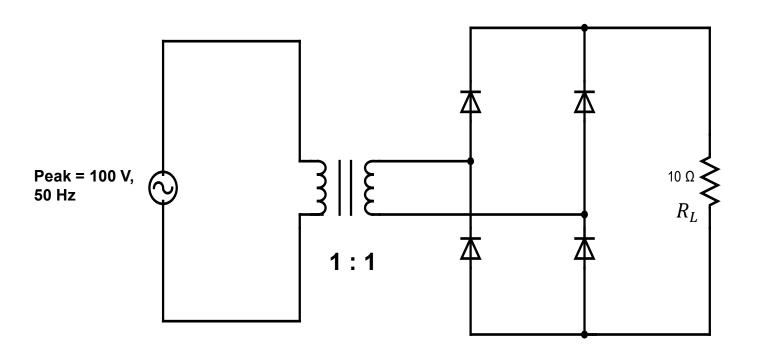
• Visualize voltage and current across  $R_L$ 

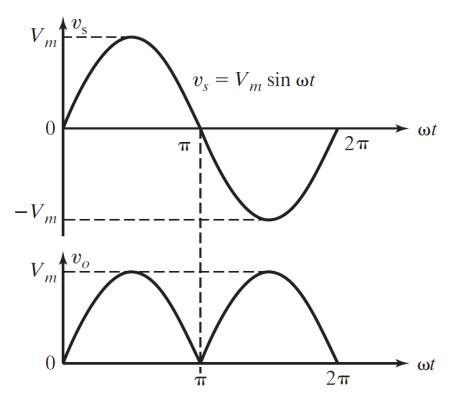




# Full Wave Bridge Rectifier

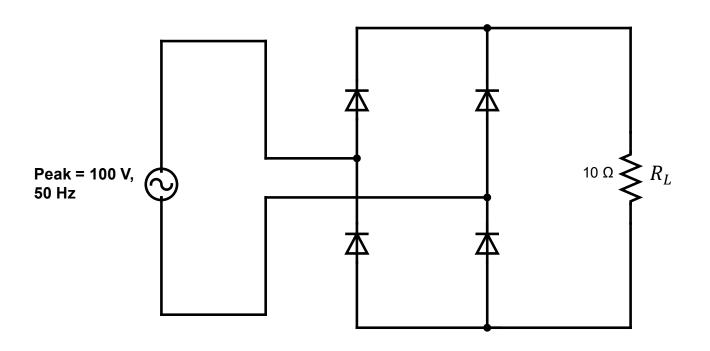
lacktriangle Visualize voltage and current across  $R_L$ 

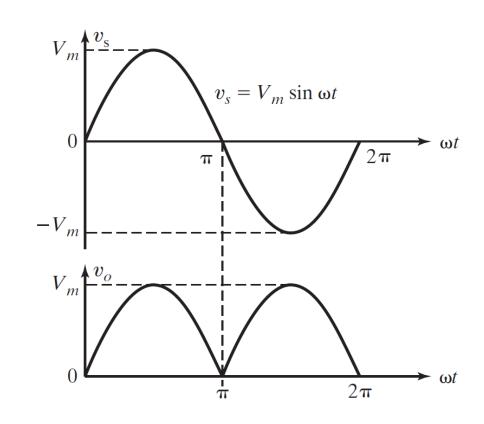




# Full Wave Bridge Rectifier

• Visualize voltage and current across  $R_L$ 

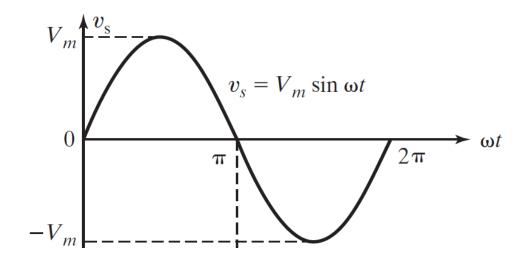




# Measurement

### **Measurement - AC**

AC Voltage or Current always measure in RMS (root mean square) value



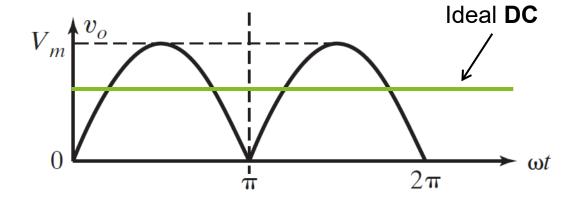
$$V_{rms} = \frac{V_m}{\sqrt{2}} = 0.707 V_m$$

$$I_{rms} = \frac{V_{rms}}{R}$$

Average value of AC Signal is always **ZERO** 

### Measurement - DC

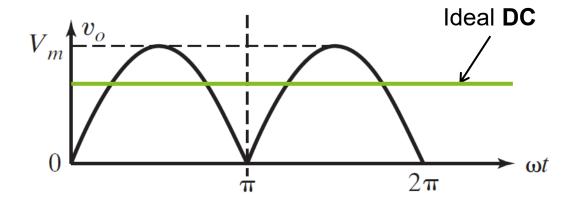
DC Voltage or Current always measure in Average value



$$V_{avg} \text{ or } V_{dc} = \frac{2V_m}{\pi} = 0.6366 V_m$$

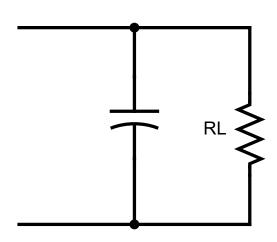
$$I_{avg}$$
 or  $I_{dc} = \frac{V_{avg}}{R}$ 

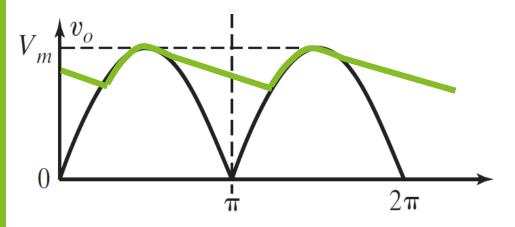
RMS value of DC Signal is **EQUAL** to AC Signal



# **Filters**

# **C** Filter





A single shunt capacitor across the load is the simplest smoothing element. It smoothens both Voltage and Current across Load

When a **capacitor** *C* is connected across the load:

- During each cycle of the input, the capacitor charges to the peak voltage  $V_m$ .
- Between peaks, the source voltage falls, but the capacitor **discharges** through the load  $R_L$ .
- This discharge causes a small drop in capacitor voltage = **ripple**  $\Delta V$ .

#### **Discharge Equations**

The current through the load is:

$$I_L = \frac{V}{R_I}$$

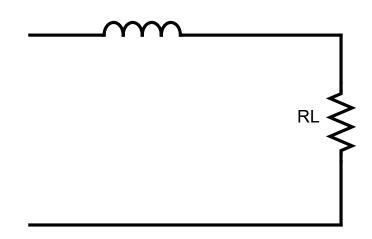
The capacitor current during discharge is:

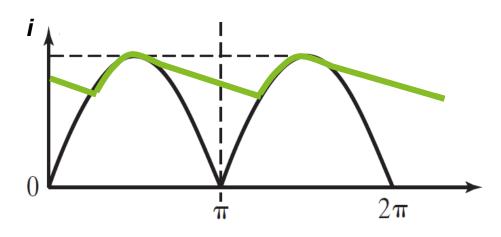
$$I_C = C \frac{dV}{dt}$$

Since the capacitor is supplying the load during the discharge interval:

$$I_L = -I_C$$

# **L** Filter





Here the inductor filters the pulsating current before it reaches the load.

**Inductor** *L* is connected in series to the load:

$$V_L = L \frac{di}{dt}$$

This means the inductor opposes sudden changes in current

- If the input is a pulsating waveform, the inductor slows down the rate of change of current, so the current delivered to the load becomes smoother.
- Since the load voltage is proportional to load current, the load voltage also become smoother.

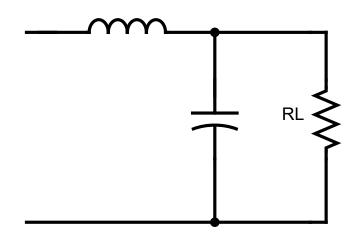
#### Advantage:

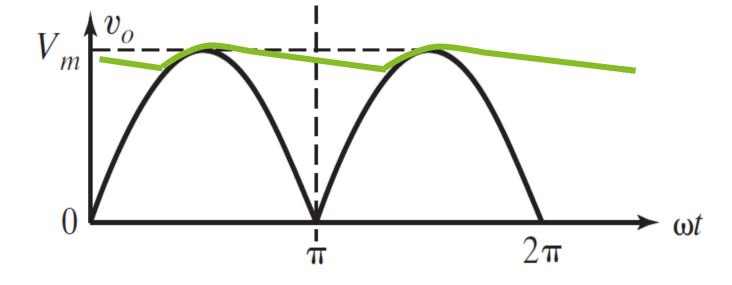
- Good current smoothing (better than simple capacitor)
- No large inrush current
- Provides continuous current

# **LC** Filter

LC filter is combination of both inductor and capacitor. This configuration reduces the pulses and make smoother.

- Inductor (L): opposes rapid changes in current, delivering a smoother current to the load.
- Capacitor (C): bypasses high-frequency AC ripple to ground, keeping the load voltage steady.

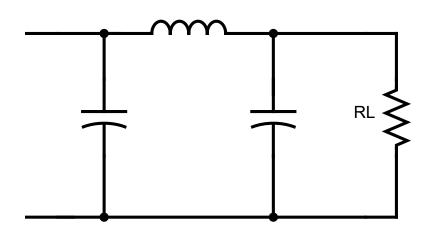


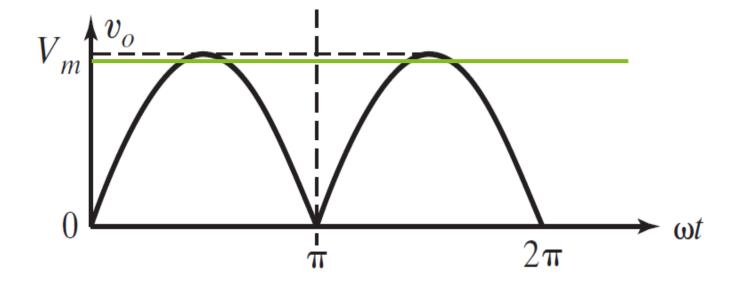


### π Filter

This circuit uses capacitor, inductor and another capacitor

- C1 (input capacitor): immediately smooths the high-frequency ripple and charges to peak voltage.
- L (inductor): opposes current ripple and further smooths variations.
- C2 (output capacitor): provides final filtering, bypassing any remaining ripple to ground



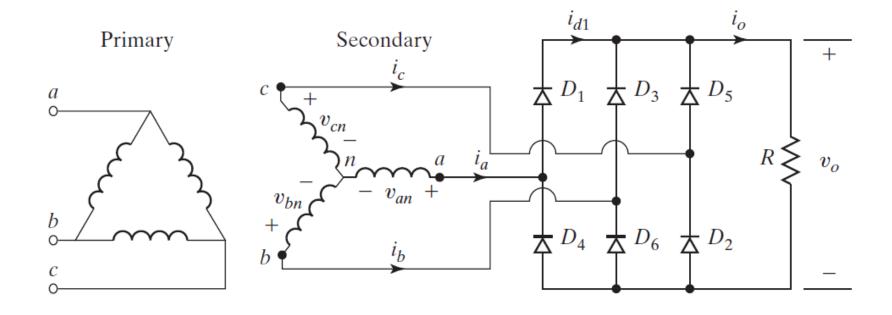


# **Three Phase Rectifier**

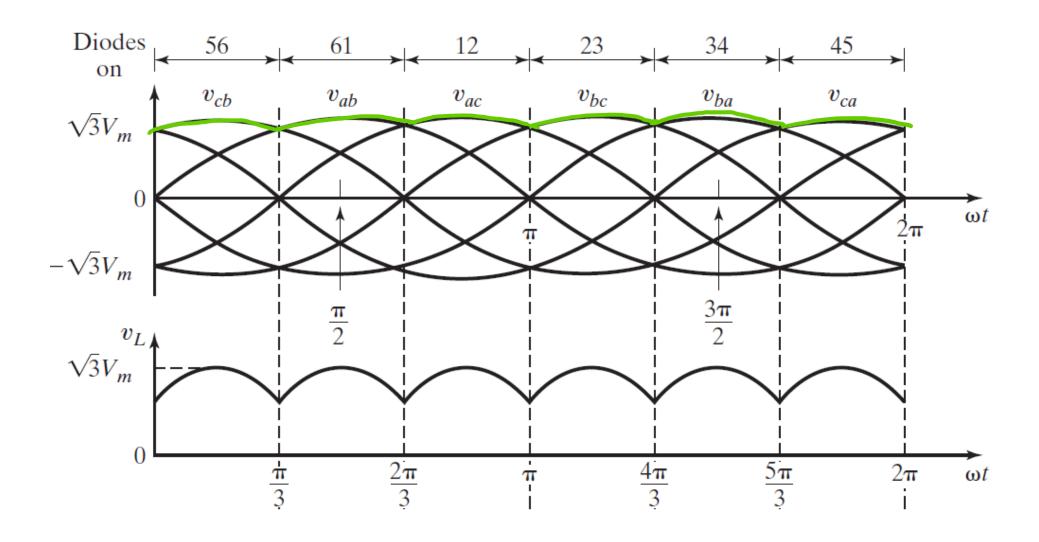
# 3 Phase Bridge Rectifier

- Full-wave rectifier, can operate with or without a transformer and gives sixpulses ripples on the output voltage.
- The conduction sequence for diodes is

*D*1 - *D*2, *D*3 - *D*2, *D*3 - *D*4, *D*5 - *D*4, *D*5 - *D*6, and *D*1 - *D*6.



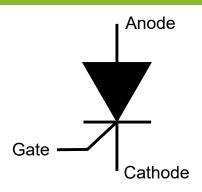
# **Output Waveform**

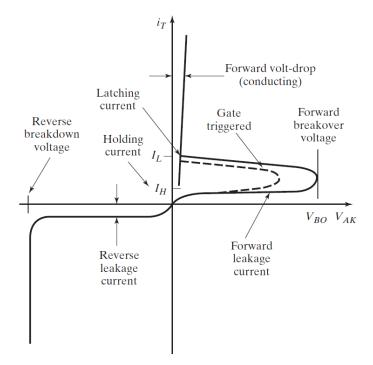


# **Controlled Rectifier**

# **Thyristor**

#### SCR – Silicon Controlled Rectifier



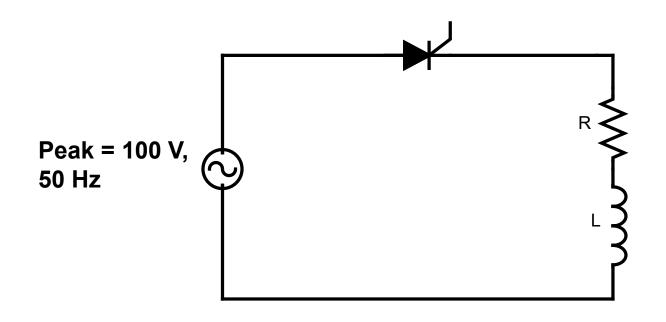


### **Properties**

- A thyristor is a four-layer semiconductor device of PNPN structure
- Can be turned ON by a gate signal
- Cannot be turned OFF by gate signal
- Once triggered ON, it remains ON even if gate signal is removed
- Turns OFF only when current falls below holding current
- Conducts current only in one direction
- Works as a controlled rectifier
- Can handle high voltage and large currents.

### Half wave-controlled rectifier

Below circuit diagram defines the half wave-controlled rectifier

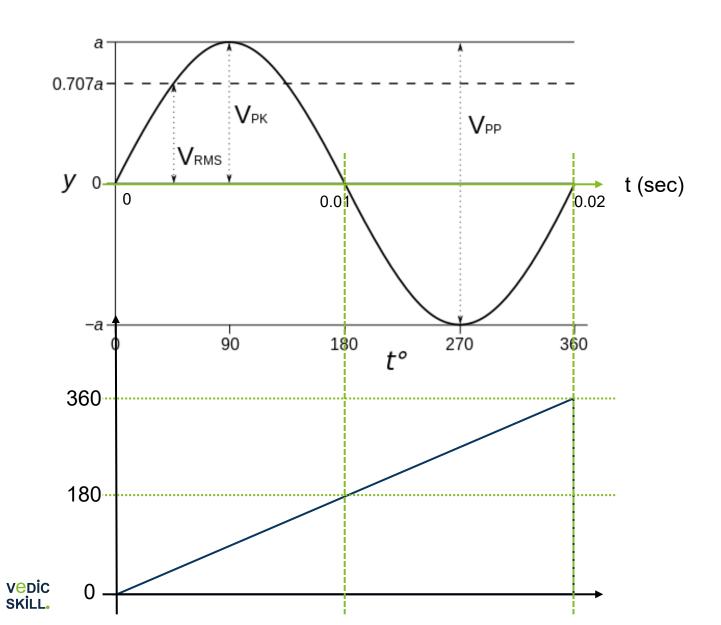


### **Explore**

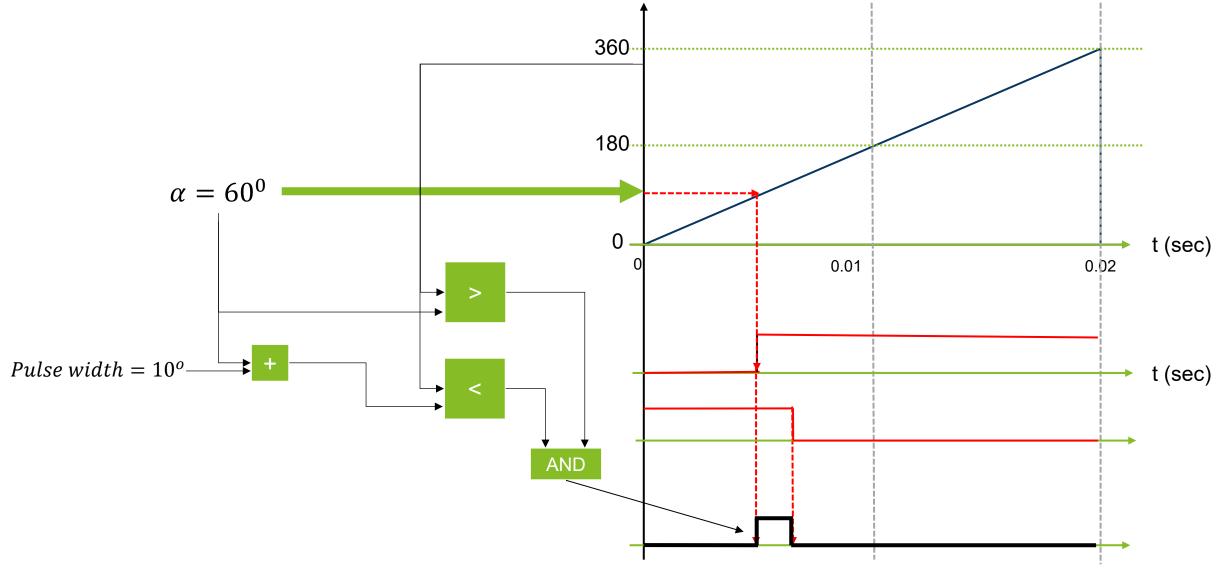
- R Load
  - Firing angle: 0, 30, 60, 90
- RL Load
  - Firing angle: 0, 30, 60, 90

# Thyristor Pulse Generator

# **Pulse Generator**



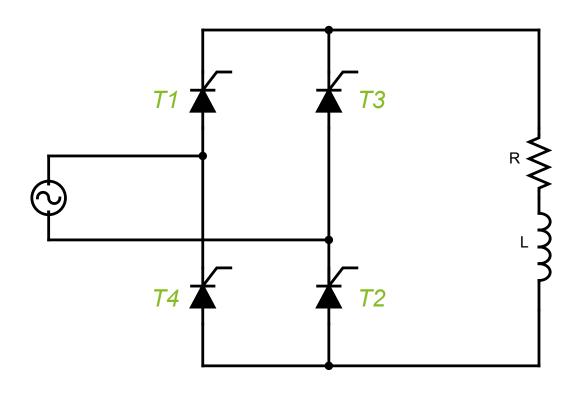
# **Pulse Generator**

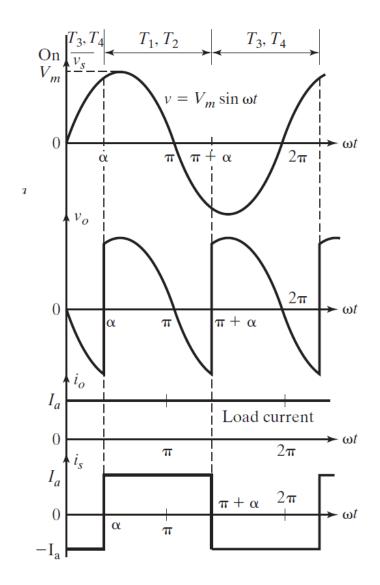


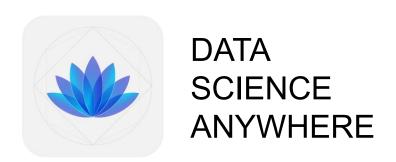
### Full wave-controlled rectifier

Condition angle: 180<sup>0</sup>

Sequence of conduction: *T1-T2, T3,T4* 









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https://github.com/datascienceanywhere



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